

# Aiyagari Model in Continuous Time with Jump-Drift Income Process\*

Alexandre Gaillard  
Toulouse School of Economics

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## 1 Model

I model [Aiyagari \(1994\)](#) with a jump-drift process for income as in [Kaplan et al. \(2016\)](#). We therefore divide the income process in permanent-transitory components.

### Income process

$$\begin{aligned} \log z &= z_j^1 + z_k^2 \\ dz_j^1 &= -\beta_1 z_j^1 dt + \epsilon_j^1 dN_j^1 \quad \text{with} \quad \epsilon_j^1 \sim \mathcal{N}(0, \sigma_1^2) \\ dz_k^2 &= -\beta_2 z_k^2 dt + \epsilon_k^2 dN_k^2 \quad \text{with} \quad \epsilon_k^2 \sim \mathcal{N}(0, \sigma_2^2) \end{aligned}$$

where, for example,  $dN_j^1$  is a pure Poisson process with arrival rate  $\lambda_1$ .

### HJB equation

$$\begin{aligned} \rho v(a, z^1, z^2) &= \max_c u(c) + v_a(a, z^1, z^2) \dot{a} + v_{z^1}(a, z^1, z^2) (-\beta_1 z^1) + v_{z^2}(a, z^1, z^2) (-\beta_2 z^2) \\ &\quad + \lambda_1 \int_x (v(a, x, z^2) - v(a, z^1, z^2)) \phi_1(x) dx \\ &\quad + \lambda_2 \int_x (v(a, z^1, x) - v(a, z^1, z^2)) \phi_2(x) dx \end{aligned}$$

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\*Corresponding author: [alexandre.gaillard@tse-fr.eu](mailto:alexandre.gaillard@tse-fr.eu). This draft is based on [Achdou et al. \(2017\)](#). All the mathematics behind this come from their work.

## 2 Numerical solution

I adopt an upwind scheme to solve the model using finite difference equation in line with [Achdou et al. \(2017\)](#). Using implicit method, the model can be rewritten in a discretized version. Let me write  $v_{i,j,k} \equiv v(a_i, z_j^1, z_k^2)$  and  $\dot{a} = wz + ra - c$ , we have:

$$\rho v_{i,j,k}^{n+1} + \frac{v_{i,j,k}^{n+1} - v_{i,j,k}^n}{\Delta} = u_{i,j,k}^n + v_{a,i,j,k}^{n+1} (we^{z_j^1 + z_k^2} + ra_i - c_{i,j,k}) + v_{z^1,i,j,k}^{n+1} (-\beta_1 z_j^1) + v_{z^2,i,j,k}^{n+1} (-\beta_2 z_k^2) \\ + \lambda_1 \sum_{j' \neq j}^{\mathcal{J}} \pi_1(j'|j) (v_{i,j',k} - v_{i,j,k}) + \lambda_2 \sum_{k' \neq k}^{\mathcal{K}} \pi_2(k'|k) (v_{i,j,k'} - v_{i,j,k})$$

which can be rewritten

$$\rho v_{i,j,k}^{n+1} + \frac{v_{i,j,k}^{n+1} - v_{i,j,k}^n}{\Delta} = u_{i,j,k}^n + \frac{v_{i+1,j,k}^{n+1} - v_{i,j,k}^{n+1}}{\Delta_{a,i,F}} s_{i,j,k}^F + \frac{v_{i,j,k}^{n+1} - v_{i-1,j,k}^{n+1}}{\Delta_{a,i,B}} s_{i,j,k}^B \\ + \frac{v_{i,j+1,k}^{n+1} - v_{i,j,k}^{n+1}}{\Delta_{z^1,j,F}} (-\beta_1 z_j^1)^+ + \frac{v_{i,j,k}^{n+1} - v_{i,j-1,k}^{n+1}}{\Delta_{z^1,j,B}} (-\beta_1 z_j^1)^- \\ + \frac{v_{i,j,k+1}^{n+1} - v_{i,j,k}^{n+1}}{\Delta_{z^2,k,F}} (-\beta_2 z_k^2)^+ + \frac{v_{i,j,k}^{n+1} - v_{i,j,k-1}^{n+1}}{\Delta_{z^2,k,B}} (-\beta_2 z_k^2)^- \\ + \lambda_1 \sum_{j' \neq j}^{\mathcal{J}} \pi_1(j'|j) (v_{i,j',k}^{n+1} - v_{i,j,k}^{n+1}) + \lambda_2 \sum_{k' \neq k}^{\mathcal{K}} \pi_2(k'|k) (v_{i,j,k'}^{n+1} - v_{i,j,k}^{n+1})$$

where, for instance,  $s_{i,j,k}^F = \max\{0, we^{z_j^1 + z_k^2} + ra_i - c_{i,j,k}^F\}$  and the operator  $+$  means  $\max\{0, x\}$ .

Using FOC, the consumption forward is equal to:

$$c_{i,j,k}^F = u'^{-1} \left( \frac{v_{i+1,j,k}^{n+1} - v_{i,j,k}^{n+1}}{\Delta_{a,i,F}} \right)$$

Grouping all terms with the same  $v$ , we get

$$\rho v_{i,j,k}^{n+1} + \frac{v_{i,j,k}^{n+1} - v_{i,j,k}^n}{\Delta} = u_{i,j,k}^n + v_{i,j,k}^{n+1} \left[ -\frac{s_{i,j,k}^F}{\Delta_{a,i,F}} + \frac{s_{i,j,k}^B}{\Delta_{a,i,B}} - \frac{(-\beta_1 z_j^1)^+}{\Delta_{z^1,j,F}} + \frac{(-\beta_1 z_j^1)^-}{\Delta_{z^1,j,B}} - \frac{(-\beta_2 z_k^2)^+}{\Delta_{z^2,k,F}} \right. \\ \left. + \frac{(-\beta_2 z_k^2)^-}{\Delta_{z^2,k,B}} - \lambda_1 \sum_{j' \neq j}^{\mathcal{J}} \pi_1(j'|j) - \lambda_2 \sum_{k' \neq k}^{\mathcal{K}} \pi_2(k'|k) \right] \\ + v_{i+1,j,k}^{n+1} \frac{s_{i,j,k}^F}{\Delta_{a,i,F}} - v_{i-1,j,k}^{n+1} \frac{s_{i,j,k}^B}{\Delta_{a,i,B}} + v_{i,j+1,k}^{n+1} \frac{(-\beta_1 z_j^1)^+}{\Delta_{z^1,j,F}} \\ - v_{i,j-1,k}^{n+1} \frac{(-\beta_1 z_j^1)^-}{\Delta_{z^1,j,B}} + v_{i,j,k+1}^{n+1} \frac{(-\beta_2 z_k^2)^+}{\Delta_{z^2,k,F}} - v_{i,j,k-1}^{n+1} \frac{(-\beta_2 z_k^2)^-}{\Delta_{z^2,k,B}} \\ + \lambda_1 \sum_{j' \neq j}^{\mathcal{J}} \pi_1(j'|j) v_{i,j',k}^{n+1} + \lambda_2 \sum_{k' \neq k}^{\mathcal{K}} \pi_2(k'|k) v_{i,j,k'}^{n+1}$$

Defining the following terms:

$$y_{i,j,k} = -\frac{s_{i,j,k}^F}{\Delta_{a,i,F}} + \frac{s_{i,j,k}^B}{\Delta_{a,i,B}} \quad x_{i,j,k} = \frac{s_{i,j,k}^F}{\Delta_{a,i,F}} \quad \xi_{i,j,k} = -\frac{s_{i,j,k}^B}{\Delta_{a,i,B}} \\ \chi_{j,k} = -\frac{(-\beta_1 z_j^1)^+}{\Delta_{z^1,j,F}} + \frac{(-\beta_1 z_j^1)^-}{\Delta_{z^1,j,B}} - \frac{(-\beta_2 z_k^2)^+}{\Delta_{z^2,k,F}} + \frac{(-\beta_2 z_k^2)^-}{\Delta_{z^2,k,B}} - \lambda_1 \sum_{j' \neq j}^{\mathcal{J}} \pi_1(j'|j) - \lambda_2 \sum_{k' \neq k}^{\mathcal{K}} \pi_2(k'|k)$$



$$\Lambda_1 = \begin{bmatrix} 0 & \dots & 0 & \pi_{2|1}^1 & 0 & \dots & 0 & \pi_{3|1} & \dots & \dots \\ \vdots & \ddots & \ddots & \ddots & \pi_{2|1}^1 & \ddots & \ddots & \ddots & \pi_{3|1}^1 & \ddots \\ 0 & \ddots & \ddots & \ddots & \ddots & \ddots & \ddots & \ddots & \ddots & \ddots \\ \pi_{1|2}^1 & 0 & \ddots & \ddots & \ddots & \ddots & 0 & \pi_{3|2}^1 & \ddots & \ddots \\ 0 & \ddots & \ddots & \ddots & \ddots & \ddots & \ddots & \ddots & \ddots & \ddots \end{bmatrix}$$

### 3 Deal with dimensionality

As dimensionality could potentially be very huge. We could divide the problem into  $K$  subproblem. We therefore use an explicit formulation for dimension  $k$ . We have to solve:

$$\begin{aligned} \rho v_{i,j,k}^{n+1} + \frac{v_{i,j,k}^{n+1} - v_{i,j,k}^n}{\Delta} &= u_{i,j,k}^n + v_{i,j,k}^{n+1} \left[ -\frac{s_{i,j,k}^F}{\Delta_{a,i,F}} + \frac{s_{i,j,k}^B}{\Delta_{a,i,B}} - \frac{(-\beta_1 z_j^1)^+}{\Delta_{z^1,j,F}} + \frac{(-\beta_1 z_j^1)^-}{\Delta_{z^1,j,B}} - \lambda_1 \sum_{j' \neq j}^{\mathcal{J}} \pi_1(j'|j) \right] \\ &+ v_{i,j,k}^n \left[ -\frac{(-\beta_2 z_k^2)^+}{\Delta_{z^2,k,F}} + \frac{(-\beta_2 z_k^2)^-}{\Delta_{z^2,k,B}} - \lambda_2 \sum_{k' \neq k}^{\mathcal{K}} \pi_2(k'|k) \right] \\ &+ v_{i+1,j,k}^{n+1} \frac{s_{i,j,k}^F}{\Delta_{a,i,F}} - v_{i-1,j,k}^{n+1} \frac{s_{i,j,k}^B}{\Delta_{a,i,B}} + v_{i,j+1,k}^{n+1} \frac{(-\beta_1 z_j^1)^+}{\Delta_{z^1,j,F}} \\ &- v_{i,j-1,k}^{n+1} \frac{(-\beta_1 z_j^1)^-}{\Delta_{z^1,j,B}} + v_{i,j,k+1}^n \frac{(-\beta_2 z_k^2)^+}{\Delta_{z^2,k,F}} - v_{i,j,k-1}^n \frac{(-\beta_2 z_k^2)^-}{\Delta_{z^2,k,B}} \\ &+ \lambda_1 \sum_{j' \neq j}^{\mathcal{J}} \pi_1(j'|j) v_{i,j',k}^{n+1} + \lambda_2 \sum_{k' \neq k}^{\mathcal{K}} \pi_2(k'|k) v_{i,j,k'}^n \end{aligned}$$

where we just replace subscript  $n+1$  by  $n$  for  $z^2$ . Because we now use explicit formulation, we have to worry about  $\Delta$ . It must be sufficiently low to respect the CFL condition, see [Barles and Souganidis \(1990\)](#). In matrix notation, we have to solve a system of  $K$  equation, such that:

$$\rho v_k^{n+1} + (v_k^{n+1} - v_k^n) \frac{1}{\Delta} = u_k^n + \mathbf{A}_k^n v_k^{n+1} + \lambda_2 \sum_{k' \neq k} \pi(k'|k) (v_{k'}^n - v_k^n) + Q_k^{+1} v_{k+1}^n + Q_k^{-1} v_{k-1}^n + Q_k v_k^n$$

$$\mathbf{A}_k^n = B_k^n + C_k + \Lambda_k$$

with notation:

$$\begin{aligned} \theta_k &= -\frac{(-\beta_2 z_k^2)^+}{\Delta_{z^2,k,F}} + \frac{(-\beta_2 z_k^2)^-}{\Delta_{z^2,k,B}} \\ \chi_j &= -\frac{(-\beta_1 z_j^1)^+}{\Delta_{z^1,j,F}} + \frac{(-\beta_1 z_j^1)^-}{\Delta_{z^1,j,B}} - \lambda_1 \sum_{j' \neq j}^{\mathcal{J}} \pi_1(j'|j) \end{aligned}$$

where the matrix  $Q_k^{-1}, Q_k, Q_k^{+1}$  are given by:

$$Q_k = \begin{bmatrix} \theta_k & 0 & \dots & \dots & \dots & \dots \\ 0 & \ddots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots & \theta_k \end{bmatrix} \quad Q_k^{+1} = \begin{bmatrix} \tilde{\beta}_k^{2,F} & 0 & \dots & \dots & \dots & \dots \\ 0 & \ddots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots & \tilde{\beta}_k^{2,F} \end{bmatrix}$$

$$Q_k^{-1} = \begin{bmatrix} \tilde{\beta}_k^{2,B} & 0 & \dots & \dots & \dots & \dots \\ 0 & \ddots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots & \tilde{\beta}_k^{2,B} \end{bmatrix}$$

## References

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